Location Based Services in LTE

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An Overview to Technology and Test Solution

LTE India May 2016

Ramarao Anil Head – product Support, Development and Applications



Where am I?







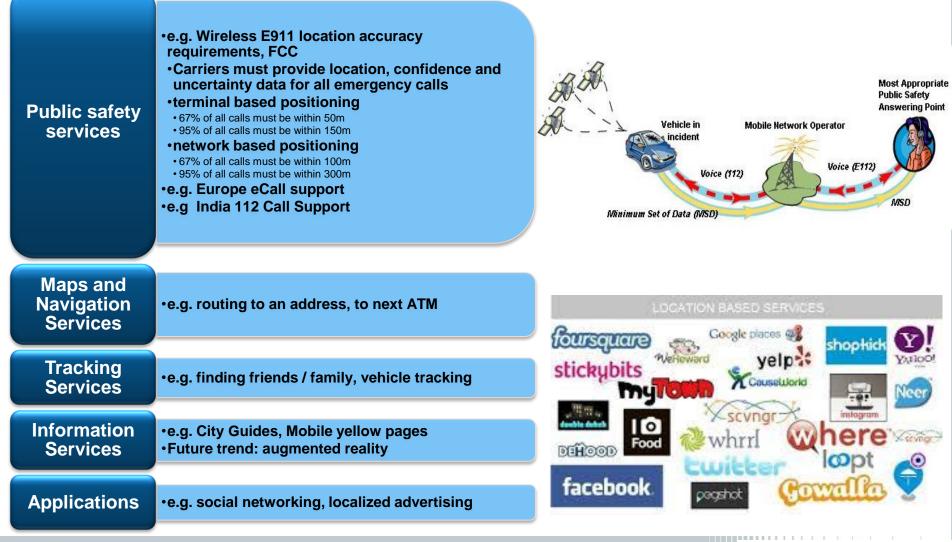


Contents

- Introduction to Location Based Services
- I Satellite based positioning
- I Network based positioning
- LBS What to test?



Positioning Technologies – Why??





Testing of these Positioning Technologies – Why??

A test solution must address the LBS 'use cases'



- 3GPP / GCF / PTCRB / OMA
- Network Operator Acceptance
- OTA Performance Testing (CTIA)
- R&D LBS Testing



FC 911





CTIA The Wireless Association

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Test Requirements:

Positioning Technologies

I Satellite based methods

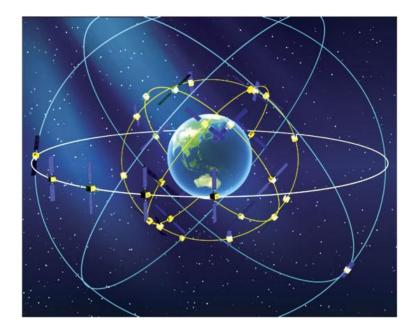
- GNSS = Global Navigation Satellite System
- I GPS, GLONASS, COMPASS/BEIDOU, GALILEO, IRNSS

I Mobile radio based methods

- I OTDOA
- l eCID

I Hybrid methods

- Combination of:
 - Multiple satellite based methods
 - Satellites and Mobile radio positioning





Satellite Based Positioning - GNSS constellations

- I GPS Global Positioning System (USA, full operation since 1995)
 - Modernized GPS (2014+) L2C, L5 (Safety of Life), new military (M) signal & other performance enhancements
- I GLONASS (Russia, full operation since October 2011)
- I BDS Beidou-2 / Compass (China, under development, operational since Dec 2011, completion in 2020)
- I Galileo (Europe, under development, target full operation 2019)
- I IRNSS (India, Compeleted in April 2016, full Operation 2016)

I SBAS – Satellite based augmentation systems

(Geostationary (regional) satellites providing additional information (e.g. error corrections) to enhance the performance of GNSS)

SDC

GAGA

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EGNOS

WAAS

- WAAS Wide Area Augmentation System (USA)
- EGNOS European Geostationary Navigation Overlay Service (Europe)
- MSAS Multi-Functional Satellite Augmentation System (Japan)
- QZSS Quasi-Zenith Satellite System (Japan)
- GAGAN GPS Aided Geo Augmented Navigation (India)



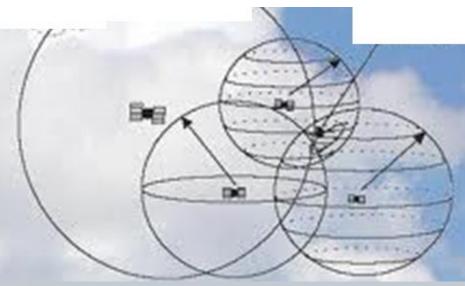
Satellite Based Positioning – How does it work?

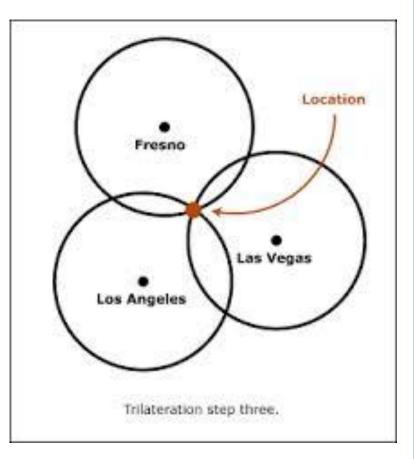
I Based on the simple idea of trilateration:

- Find <u>coordinates</u> of at least three objects
- I Find the distance to each of these objects
- I Intersecting point of 3 circles is your 2D position

I And apply this to satellites and a receiver:

- I Find coordinates of at least FOUR satellites
- I Find the distance to each of these satellites
- I Intersecting point of the 4spheres is your 3D position





While is makes sense that three sats would be enough (since you can rule out being in the middle of the planet or up in the sky), 4 are still needed to overcome the problem of inaccurate quartz clocks in gnss receivers



Assisted A-GNSS

- I The network assists the device GNSS receiver to improve the performance in several aspects:
 - I Reduce GNSS start-up and acquisition times.
 - I Increase GNSS sensitivity, reduce power consumption.
 - I Gives the GNSS receiver a jump start!

Two modes

I Mobile assisted mode

 Device (= User Equipment, UE) transmits GNSS measurement results to network server, where position calculation takes place.

I Mobile based mode

- UE performs GNSS measurements and position calculation
- Using Data to assist in GNSS measurements and position calculations, e.g. reference time, visible satellite list, reference position, satellite ephemeris, etc.

Assistance Data			
Reference Time			
Reference Location			
Ionospheric Models			
Earth Orientation Parameters			
GNSS-GNSS Time Offsets			
Differential GNSS Corrections			
Ephemeris and Clock Models			
Real-Time Integrity			
Data Bit Assistance			
Acquisition Assistance			
Almanac			
UTC Models			





Why sometimes even A-GNSS is not enough...



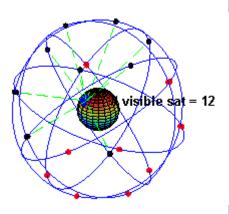
Critical scenario

Very critical scenario

GPS Satellites visibility (Urban)

I Global navigation satellite systems (GNSSs)

- are designed for continuous reception, outdoor
- have restricted performance in certain environments
 - GNSS is low power and relatively high frequency (easily blocked)



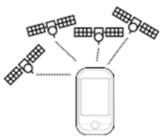
Reference [DLR]

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- Often less than four satellites visible: critical situation for GNSS positioning
 - \rightarrow alternatives required (Mobile radio positioning)



GNSS vs. Mobile radio positioning methods





GNSS	Mobile radio systems	
Low bandwidth (1-2 MHz)	High bandwidth (up to 20 MHz in LTE)	
Very weak received signals	Comparatively strong received signals	
Similar received power levels from all satellites	One strong signal from the serving BS, strong interference situation	
Long synchronization sequences	Short synchronization sequences	
Signal a-priori known due to low data rates	Complete signal not a-priori known to support high data rates, only certain pilots	
Very accurate synchronization of the satellites by atomic clocks	Synchronization of the BSs not a-priori guaranteed	
Line of sight (LOS) access as normal case \rightarrow not suitable for urban / indoor areas	Non line of sight (NLOS) access as normal case → suitable for urban / indoor areas	
3-dimensional positioning	2-dimensional positioning	



Reference [DLR]

LTE supports the following positioning techniques:

I AGNSS based positioning using different GNSS constellations (or even combinations)

Sub-Test Case Number	Supported GNSS		
1	UE supporting A-GLONASS only		
2	UE supporting A-Galileo only		
3	UE supporting A-GPS and Modernized GPS only		
4	UE supporting A-GPS and A-GLONASS only		

- A-GNSS (using GPS, GLONASS, GALILEO, BEIDOU-2, IRNSS)

I Mobile radio based positioning methods

- OTDOA, UTDOA, eCID etc.

I Hybrid methods

Intelligent switching/combining of different methods for more reliability towards different scenarios

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LTE supported positioning methods

- I Satellite positioning method:
- I Network positioning methods:

A-GNSS OTDOA, eCID, UTDOA

Reference: 3GPP TS 36.305

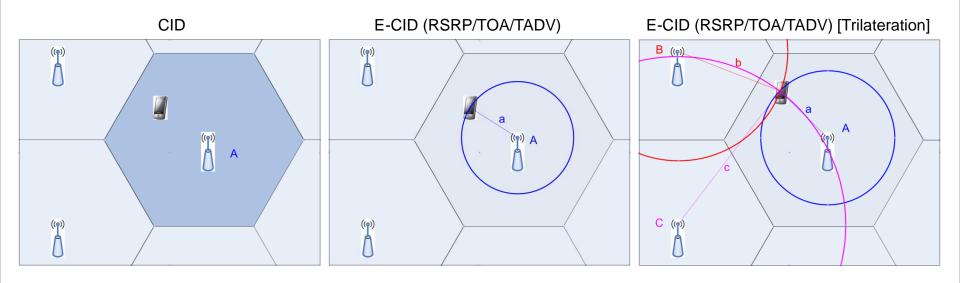
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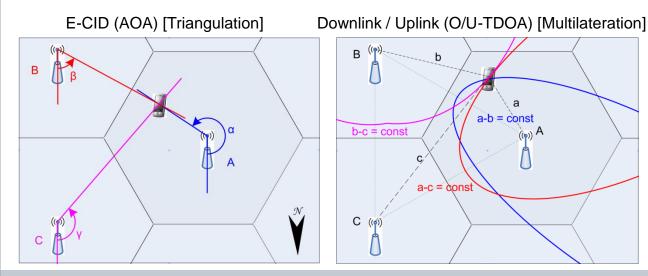
Method	UE-based	UE-assisted	eNB-assisted	3GPP Release
A-GNSS	Yes Measurement: UE Estimation: UE	Yes Measurement: UE Estimation: LS	No	Rel-9
Downlink (OTDOA)	No	Yes Measurement: UE Estimation: LS	No	Rel-9
Enhanced Cell ID (eCID)	No	Yes Measurement: UE Estimation: LS	Yes Measurement: eNB Estimation: LS	Rel-9
Uplink (UTDOA)	No	No	Yes Measurement: eNB Estimation: LS	Rel-11

- I Measurements are performed by UE or eNB
- I Position estimations are performed by UE or LS (Location Server)



Methods' overview





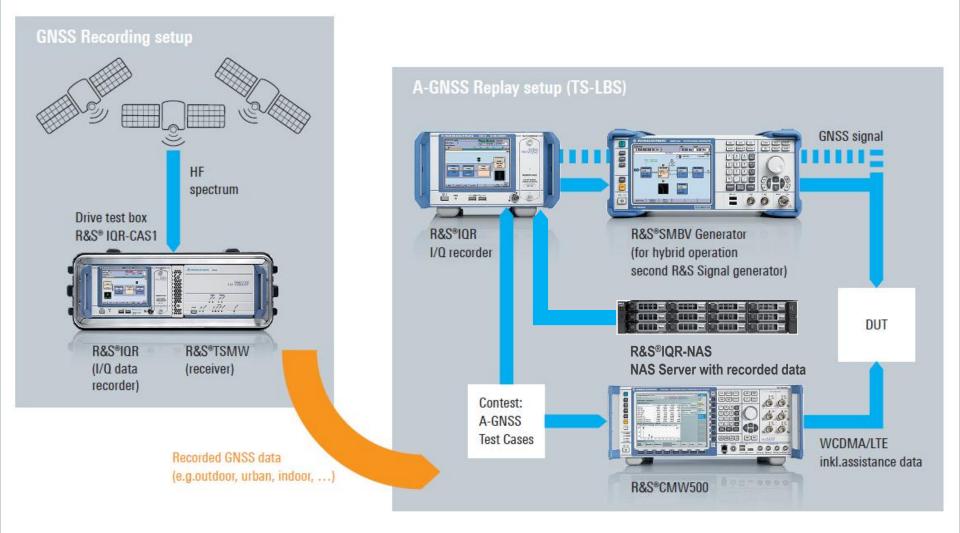


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LBS – Field to Lab (F2L)



A-GNSS Record Replay solution



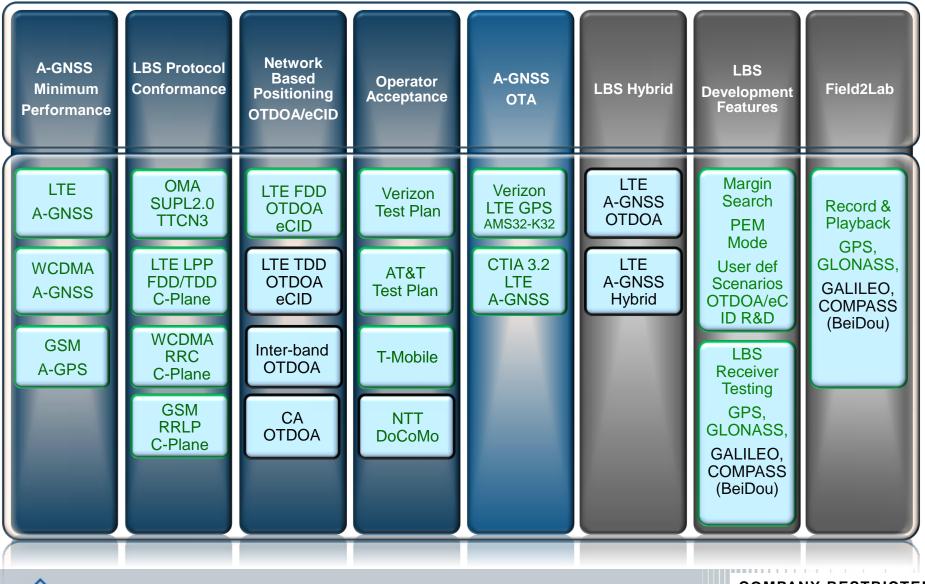
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LBS – What to test?



LBS general overview



ROHDE&SCHWARZ

TS-LBS A-GNSS set up

Capabilities (2G/3G/LTE) Min Perf

•RF minimum performance

- •2G: TS51.010-1 sections 70.11.x, 70.16.x
- •3G: TS37.571-1 section 5/6
- •LTE: TS37.571-1 section 7
- •SUPL •Network operator specific test cases •GPS, GLONASSS, GALILEO & COMPASS

Capabilities (2G/3G/LTE) protocol

•A-GNSS protocol conformance

- •2G: TS51.010-1
- •3G: TS34.123 / TS37.571-2
- •LTE: TS37.571-2
- •SUPL

•Network operator specific test cases •GPS, GLONASSS, GALILEO & COMPASS

Benefits

•Small form factor •CONTEST for execution:

- •Automation
- •Reporting, Database,...
- Upgradeable to OTDOA/ECID

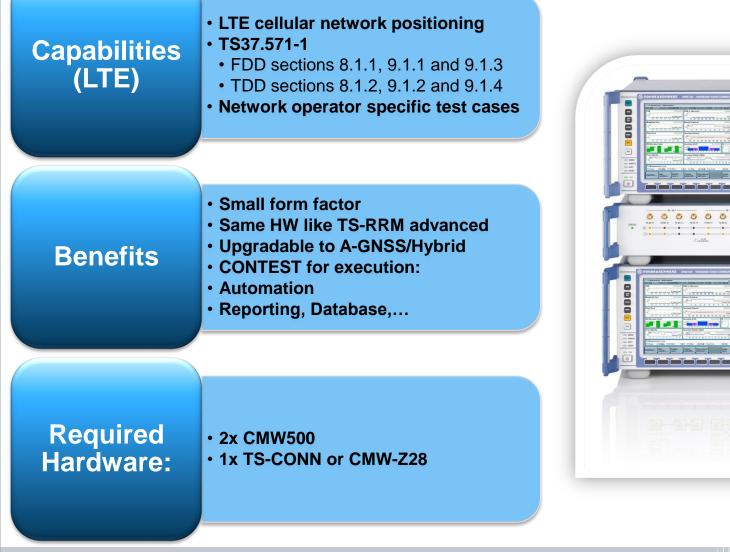
Hardware Setup

- Dedicated, small system:
 - CMW500
 - SMBV100A
 - Control PC
 - CONTEST Software + Test Cases



TS-LBS Advanced OTDOA/eCID Setup

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Thank you for your attention!



